## **Fangzhou Lin**

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#### EDUCATION

#### Worcester Polytechnic Institute (WPI)

Visiting Ph. D. Student in Electrical & Computer Engineering (VISLab)

#### TOHOKU UNIVERSITY

Doctor of Philosophy
Majors: Information Sciences and Data Sciences
Cumulative GPA: 4.0/4.0; Major GPA: 4.0/4.0

#### TOHOKU UNIVERSITY

Master of Information Sciences
Major: Information Sciences
Cumulative GPA: 3.8/4.0; Major GPA: 4.0/4.0

#### **PAPER/PUBLICATION**

- Lin F, Liu H, Wang L, Yamada KD, Kolachalama VB, Zhang KH, Zhang Z, SIMEX: Deep Similarity Learning for Set-to-Set Matching with Extreme Value Distribution Prior. European Conference on Computer Vision (ECCV) 2024 (Under review)
- Lin F, Liu H, Zhou H, Hou S, Yamada KD, Fischer G, Li Y, Zhang KH, Zhang Z, Loss Distillation via Gradient Matching for Point Cloud Completion with Weighted Chamfer Distance. International Conference on Intelligent Robots and Systems (IROS) 2024 (Under review)
- 3. Lin F, Gao S, Tang Y, Xu P, Ma X, Hou S, Zhang Z, Zhang KH, Zero-Shot Hybrid: Photoacoustic Imaging Denoising with Noisy Data Only. Medical Image Computing and Computer Assisted Intervention (MICCAI) 2024 (Under review)
- 4. Yue Y, Lin F, Guanyi Mou, Zhang Z, Understanding Hyperbolic Metric Learning through Hard Negative Sampling. In Proceeding of Winter Conference on Applications of Computer Vision (WACV), 2024.
- Lin F, Yue Y, Zhang Z, Hou S, Yamada KD, Kolachalama VB, Saligrama V, InfoCD: A Contrastive Chamfer Distance Loss for Point Cloud Completion. In Proceeding of Advances in Neural Information Processing Systems (NeurIPS), 2023.
- 6. Lin F, Yue Y, Hou S, Yu X, Xu Y, Yamada KD, Zhang Z, Hyperbolic Chamfer Distance for Point Cloud Completion. In Proceeding of International Conference on Computer Vision (ICCV), 2023.
- 7. Yamada KD, Baladram MS, Lin F, Relation is an option for processing context information, Frontiers in Artificial Intelligence, Frontiers in Artificial Intelligence, 5:924688, 2022.
- 8. Gao C, Cai G, Jiang X, Zheng F, Zhang J, Gong Y, Lin F, Sun X, Bai X. Conditional Feature Learning based Transformer for Text-Based Person Search. IEEE Transactions on Image Processing. 2022 Sep 14.
- 9. Lin F, Xu Y, Zhang Z, Gao C, Yamada KD, Cosmos Propagation Network: Deep Learning Model for Point Cloud Completion, Neurocomputing, 507:221-234, 2022.
- 10. Yamada KD, Baladram MS, Lin F, Progress in research on implementing machine consciousness, Interdisciplinary Information Sciences, 28(1):95-105, 2022.
- 11. Xu Y, Arai S, Liu D, Lin F, Kosuge K, FPCC: Fast Point Cloud Clustering-based Instance Segmentation for Industrial Bin-picking. Neurocomputing, 2022, ISSN 0925-2312.
- 12. Lin F, Gao C, Yamada KD, An effective convolutional neural network for visualized understanding transboundary air pollution based on Himawari-8 satellite images, IEEE Geoscience and Remote Sensing Letters, 2021, 19, 1-5.
- 13. Yamada KD, Lin F, Nakamura T, Developing a novel recurrent neural network architecture with fewer parameters and good learning performance, Interdisciplinary Information Sciences, 27(1):25-40, 2021.
- 14. Xu Y, Arai S, Liu D, Lin F, Kosuge K, FPCC: Fast Point Cloud Clustering for Instance Segmentation. arXiv preprint arXiv:2012.14618.(2020).
- 15. Yue Y, Lin F, Yamada KD, Zhang Z, Hyperbolic contrastive learning. arXiv preprint arXiv:2302.01409. (2023).

Worcester, MA, USA Oct. 2021-Jan. 2024

Sendai, Japan April. 2021-Jan. 2024

Sendai, Japan Apr.2020 - Mar. 2021

#### **RESEARCH EXPERIENCE** Working on Photoacoustic (PA) image denoising Worcester, MA, USA Under the supervision of Prof. Haichong K. Zhang in Medical FUSION Lab Jan.2024-Present Explored the possibility of Zero-shot and Data-free methods work together on PA image denoising. Proposed a novel algorithm for multi-frame PA image denoising in same interest-region. Observed feasible performance improvement on phantom, ex vivo, and in vivo data of PA image denoising. Submission: Zero-Shot Hybrid: Photoacoustic Imaging Denoising with Noisy Data Only. Medical Image Computing and Computer Assisted Intervention (MICCAI) 2024 (Under review) Working on solely diffusion model-based point cloud registration Worcester, MA, USA Under the supervision of Prof. Ziming Zhang in VISLab and Prof. Yamada Nov.2023-Present Explored the possibility of diffusion model solely on point cloud registration task. Introduced straight Brownian Bridge Diffusion Model to this task without the usage of ICP. **Designing SIMEX for set-to-set matching** Worcester, MA, USA Under the supervision of Prof. Ziming Zhang in VISLab and Prof. Yamada Nov.2023- Present Explored the reasoning of set-to-set match and the possibility of removing the high cost EMD method. Proposed a novel framework for set-to-set match with Extreme Value Distribution Prior (SIMEX). • Reached SOTA in both point cloud completion and Few-Shot Classification tasks. Submission: SIMEX: Deep Similarity Learning for Set-to-Set Matching with Extreme Value Distribution Prior. European Conference on Computer Vision (ECCV) 2024 (Under review) Designing loss distillation via gradient matching for point cloud completion Worcester, MA, USA Under the supervision of Prof. Ziming Zhang in VISLab and Prof. Yamada May.2023-Mar.2024 Explored the loss metric design without grid search in real data but only mathematic derivations. Proposed a novel loss function search pipeline, namely Loss Distillation via Gradient Matching. Found a loss function family and reached SOTA in several point cloud completion benchmarks. Submission: Loss Distillation via Gradient Matching for Point Cloud Completion with Weighted Chamfer Distance. International Conference on Intelligent Robots and Systems (IROS) 2024 (Under review) Designing contrastive loss for point cloud completion task Worcester, MA, USA Under the supervision of Prof. Ziming Zhang in VISLab and Prof. Yamada May.2023- Sep.2023 Explored the loss function design with contractive learning. • Proposed a regularized CD metric which is robust and computationally efficient. Reached SOTA in several point cloud completion benchmarks. Publication: A Contrastive Chamfer Distance Loss for Point Cloud Completion. In Proceeding of Advances in Neural Information Processing Systems (NeurIPS), 2023. Designing hyperbolic loss for point cloud completion task Worcester, MA, USA

Under the supervision of Prof. Ziming Zhang in VISLab and Prof. Yamada

- Explored the loss function design rather than Euclidean space but in Hyperbolic space.
- Analysis the gradient behavior of proposed loss function with in-depth comparisons.

• Reached SOTA in several point cloud completion benchmarks and visual superiority.

**Publication:** Hyperbolic Chamfer Distance for Point Cloud Completion. In Proceeding of International Conference on Computer Vision (ICCV), 2023.

Oct.2022-May.2023

# Designing a novel network for point cloud completion taskWorcester, MA, USAUnder the supervision of Prof. Ziming Zhang in VISLab and Prof. YamadaMay.2021-Dec.2021

- Proposed a novel neural network architecture, CP-Net, for point cloud completion task.
- Reached SOTA in shapenet-part benchmark.

Publication: Cosmos Propagation Network: Deep Learning Model for Point Cloud Completion, Neurocomputing, 2022

### SKILLS

- **Programming Languages:** Python, MATLAB, C/C++, CUDA
- Engineering/System Skills: Linux, Docker, ROS, SolidWorks
- Language: Chinese (Native or bilingual proficiency), English (Full professional proficiency), Japanese (N1 and N2, Good/conversational)